

Momento angular cuántico V

$$\vec{L} = \vec{R} \times \vec{p} \rightarrow [J_i, J_j] = i\hbar \epsilon_{ijk} J_k$$

$$\begin{cases} J^2 |j m\rangle = \hbar^2 j(j+1) |j m\rangle \\ J_z |j m\rangle = \hbar m |j m\rangle \end{cases}$$

$$\begin{cases} \vec{L} = \vec{R} \times \vec{p} & \langle \vec{r} | \vec{R} | \psi \rangle = \vec{r} \psi(x) \\ & \langle \vec{r} | \vec{p} | \psi \rangle = -i\hbar \vec{\nabla} \psi(x) \end{cases}$$

$$\left\{ \begin{array}{l} - \left[\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right] \psi(r, \theta, \varphi) = l(l+1) \psi(r, \theta, \varphi) \quad (\text{D-7-a}) \\ - i \frac{\partial}{\partial \varphi} \psi(r, \theta, \varphi) = m \psi(r, \theta, \varphi) \quad (\text{D-7-b}) \end{array} \right.$$

$$L^2 \psi(r, \theta, \varphi) = \hbar^2 l(l+1) \psi(r, \theta, \varphi)$$

$$L_z \psi(r, \theta, \varphi) = \hbar m \psi(r, \theta, \varphi)$$

$$\psi(r, \theta, \varphi) = f(r) Y_l^m(\theta, \varphi)$$

$$L^2 Y_l^m(\theta, \varphi) = \hbar^2 l(l+1) Y_l^m(\theta, \varphi)$$

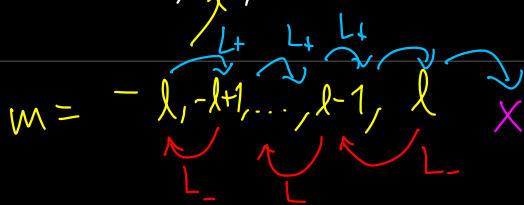
$$L_z Y_l^m(\theta, \varphi) = \hbar m Y_l^m(\theta, \varphi)$$

$$Y_l^m(\theta, \varphi) = F_l^m(\theta) e^{im\varphi}$$

entero
 $\therefore l$ entero
 $Y_l^m(\theta, \varphi) = Y_l^m(\theta, \varphi + 2\pi)$

- Método algebraico para encontrar $Y_l^m(\theta, \varphi)$
 - $\rightarrow L_+ Y_l^{m=l}(\theta, \varphi) = 0$ resolver para $Y_l^l(\theta, \varphi)$
 - \rightarrow Aplicando L_- varias veces obtener $Y_l^m(\theta, \varphi)$

$$L_{\pm} |l, m\rangle = \hbar \sqrt{l(l+1) - m(m\pm 1)} |l, m\pm 1\rangle$$



$$\vec{L} = \vec{r} \times \vec{p} \quad \langle \vec{r} | \vec{L} | \psi \rangle = -i\hbar \vec{r} \times \vec{\nabla} \psi(\vec{r}) \Rightarrow \vec{L} \sim \frac{\hbar}{\lambda} \vec{r} \times \vec{\nabla}$$

$L_x = \frac{\hbar}{i} \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right)$ $L_y = \frac{\hbar}{i} \left(z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z} \right)$ $L_z = \frac{\hbar}{i} \left(x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right)$	en estéricos →	$L_x = i\hbar \left(\sin \varphi \frac{\partial}{\partial \theta} + \frac{\cos \varphi}{\tan \theta} \frac{\partial}{\partial \varphi} \right)$ $L_y = i\hbar \left(-\cos \varphi \frac{\partial}{\partial \theta} + \frac{\sin \varphi}{\tan \theta} \frac{\partial}{\partial \varphi} \right)$ $L_z = \frac{\hbar}{i} \frac{\partial}{\partial \varphi}$
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↓

$$L_+ = \hbar e^{i\varphi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \varphi} \right)$$

$$L_- = \hbar e^{-i\varphi} \left(\frac{\partial}{\partial \theta} - i \cot \theta \frac{\partial}{\partial \varphi} \right)$$

$$L_+ Y_l^l(\theta, \varphi) = \hbar e^{i\varphi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \varphi} \right) Y_l^l(\theta, \varphi) = 0$$

$$\Rightarrow \text{Usando } \underline{Y_l^m(\theta, \varphi)} = F_l^m(\theta) e^{im\varphi}$$

$$\Rightarrow 0 = \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \varphi} \right) \left[F_l^l(\theta) e^{il\varphi} \right] = \left(\frac{\partial}{\partial \theta} - l \cot \theta \right) F_l^l(\theta) = 0$$

$$\Rightarrow \frac{dF_l^l(\theta)}{d\theta} = l \frac{\cos \theta}{\sin \theta} F_l^l(\theta) \Rightarrow \frac{1}{F_l^l(\theta)} \frac{dF_l^l(\theta)}{d\theta} = l \frac{\cos \theta}{\sin \theta}$$

De ambos lados hay $\frac{g}{g}$

$$\ln F_l^l(\theta) = l \ln \sin \theta \Rightarrow F_l^l(\theta) = \sin^l(\theta)$$

$$Y_l^l(\theta, \varphi) = N \sin^l(\theta) e^{il\varphi}$$

← constante de normalización

Normalizamos con

$$\int_0^{2\pi} \int_0^\pi |Y_l^l(\theta, \varphi)|^2 \sin \theta d\theta d\varphi = 1$$

$l = 0$	$l = 1$	$l = 2$
$Y_0^0 = \sqrt{\frac{1}{4\pi}}$	$Y_1^{\pm 1} = \pm \sqrt{\frac{3}{8\pi}} \sin \theta e^{\pm i\varphi}$ $Y_1^0 = \sqrt{\frac{3}{4\pi}} \cos \theta$	$Y_2^{\pm 2} = \sqrt{\frac{15}{32\pi}} \sin^2 \theta e^{\pm 2i\varphi}$ $Y_2^{\pm 1} = \mp \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{\pm i\varphi}$ $Y_2^0 = \sqrt{\frac{5}{16\pi}} (3 \cos^2 \theta - 1)$

La expresión general para cualquier valor de l y m está dada por

$$Y_l^m(\theta, \varphi) = (-1)^m \sqrt{\frac{(2l+1)(l-m)!}{4\pi(l+m)!}} P_l^m(\cos \theta) e^{im\varphi}, \quad m \geq 0;$$

$$Y_l^{-m}(\theta, \varphi) = (-1)^m Y_l^m(\theta, \varphi)^*;$$

$$P_l^m(x) = (1-x^2)^{|m|/2} \frac{d^{|m|}}{dx^{|m|}} P_l(x);$$

$$P_l(x) = \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2 - 1)^l.$$

Aquí, a $P_l^m(x)$ se le conoce como polinomio asociado de Legendre.

Python
RELEASE 1.8.0

scipy.special.sph_harm

scipy.special.sph_harm(m, n, theta, phi) = <ufunc 'sph_harm'>
Compute spherical harmonics.

The spherical harmonics are defined as

$$Y_n^m(\theta, \phi) = \sqrt{\frac{2n+1}{4\pi} \frac{(n-m)!}{(n+m)!}} e^{im\phi} P_n^m(\cos(\theta))$$

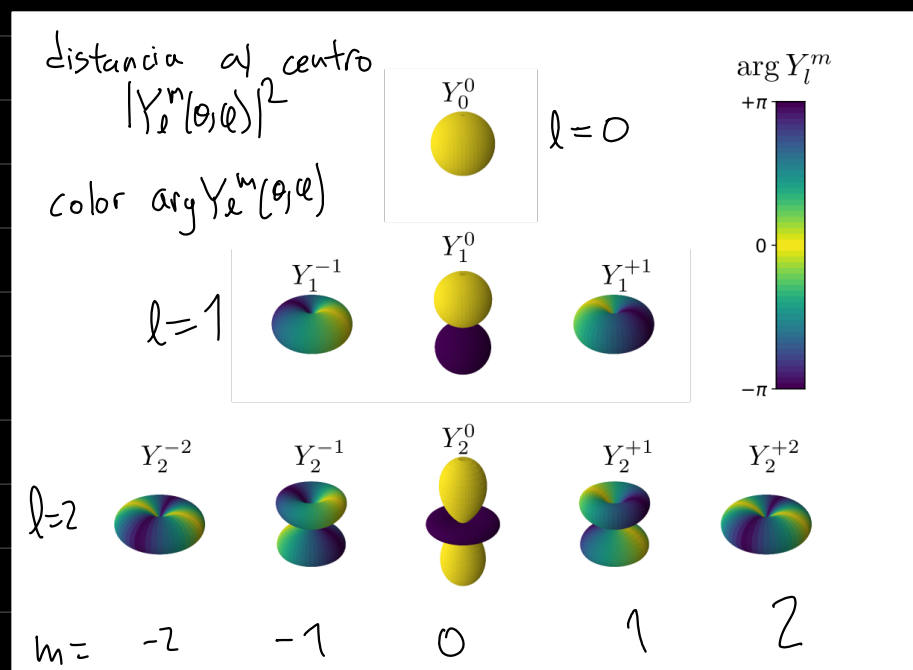
where P_n^m are the associated Legendre functions; see `lpmv`.

BUILT-IN SYMBOL

Mathematica
SphericalHarmonicY

SphericalHarmonicY[l, m, theta, phi]
gives the spherical harmonic $Y_l^m(\theta, \phi)$.

Ojo con la convención usada en cada programa.



- Valores esperados de eigenestados de momento angular.

Considerando $|l, m\rangle$ e-vector de L^2 y L_z

$$\langle L^2 \rangle = \langle l, m | L^2 | l, m \rangle = \hbar^2 l(l+1) \langle l, m | l, m \rangle = \hbar^2 l(l+1)$$

$$\langle L_z \rangle = \hbar m$$

$$\langle L_x \rangle = \langle \frac{1}{2}(L_+ + L_-) \rangle = \frac{1}{2} \langle l, m | L_+ + L_- | l, m \rangle = \frac{1}{2} [\langle l, m | L_+ | l, m \rangle + \langle l, m | L_- | l, m \rangle] = 0$$

$$L_{\pm} | l, m \rangle = \hbar \sqrt{l(l+1) - m(m \pm 1)} | l, m \pm 1 \rangle$$

$$\langle L_y \rangle = 0$$

$$\Delta L_x^2 = \langle L_x^2 \rangle = \frac{1}{4} \langle l, m | L_+^2 + L_+ L_- + L_- L_+ + L_-^2 | l, m \rangle$$

Recordando

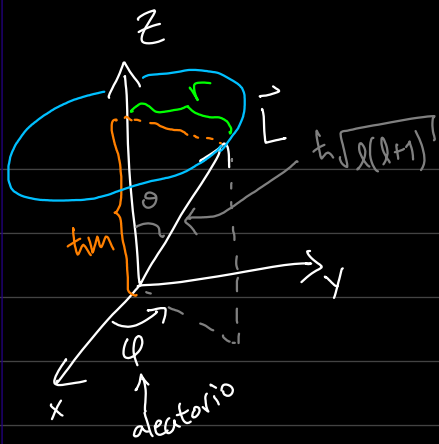
$$J^2 = \frac{1}{2}(J_+ J_- + J_- J_+) + J_z^2 \rightarrow L_+ L_- + L_- L_+ = 2(J^2 - J_z^2)$$

$$\langle L_x^2 \rangle = \frac{\hbar^2}{2} [l(l+1) - m^2]$$

$$\Delta L_y^2 = \langle L_y^2 \rangle = \langle \left(\frac{L_+ - L_-}{2i} \right)^2 \rangle = \langle -\frac{1}{4} (L_+ - L_-)^2 \rangle = -\frac{1}{4} \langle L_+^2 - L_+ L_- - L_- L_+ + L_-^2 \rangle = \dots = \frac{\hbar^2}{2} [l(l+1) - m^2]$$

$$\Delta L_x = \Delta L_y = \hbar \sqrt{\frac{1}{2} [l(l+1) - m^2]}$$

$$\Delta L_z^2 = \langle l, m | L_z^2 | l, m \rangle - \langle l, m | L_z | l, m \rangle^2 = 0$$

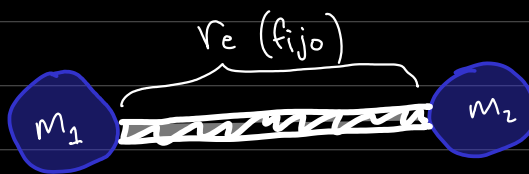


Por teorema de Pitágoras,
el **radio** del círculo

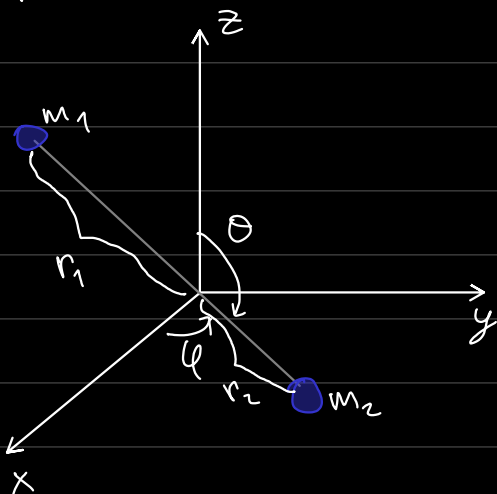
$$r^2 = h^2 l(l+1) - h^2 m^2$$

$$r = h \sqrt{l(l+1) - m^2}$$

Ejemplo rotor rígido.



Tratamiento clásico



- origen en Centro de masa

$$m_1 r_1 = m_2 r_2$$

- Distancia fija $r_1 + r_2 = r_e$

- $I = m_1 r_1^2 + m_2 r_2^2$ momento de inercia

- $\mu = \frac{m_1 m_2}{m_1 + m_2}$ masa reducida

$$I = \mu r_e^2$$

- Si no hay fuerzas externas, el momento angular \vec{L} respecto al c.m. es constante.

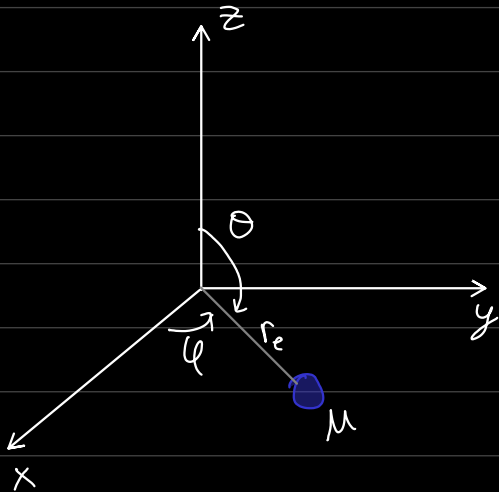
i.e. el rotor gira con frecuencia angular ω_R constante en el plano perpendicular a \vec{L} .

$$|\vec{L}| = r_1 m_1 r_1 \omega_R + r_2 m_2 r_2 \omega_R = I \omega_R = \mu r_e^2 \omega_R$$

La energía es la cinética rotacional.

$$H = \frac{1}{2} m \omega_R^2 = \frac{L^2}{2I} = \frac{L^2}{2\mu r_e^2}$$

Podemos ver al sistema como una partícula ficticia de masa μ separada r_e del origen y que gira con vel. angular ω_R .
 L es el momento angular de la partícula.



Caso cuántico.

El estado del rotor está descrito por

$$\psi(\theta, \varphi) \quad \left(r \text{ no importa porque } r_e \text{ es fijo} \right)$$

$|\psi(\theta, \varphi)|^2 \sin\theta d\theta d\varphi$ es la probabilidad de encontrar al rotor apuntando hacia θ, φ .

$$H = \frac{L^2}{2\mu r_e^2}$$

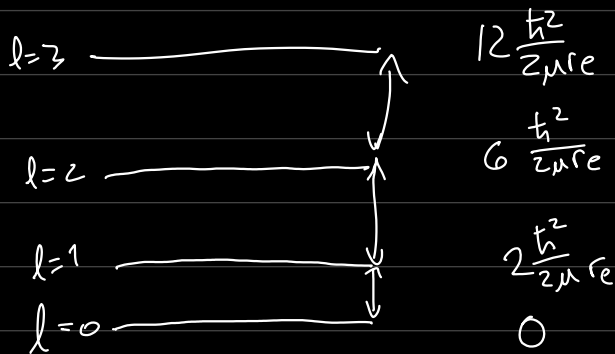
Encontrar los e-valores y e-vectores de H se reduce a encontrar los de L^2

$$\Rightarrow H |l, m\rangle = \frac{\hbar^2 l(l+1)}{2\mu r_e} |l, m\rangle$$

$\leftarrow E_{lm}$

$$\psi_l^m(\theta, \varphi) = Y_l^m(\theta, \varphi)$$

Cada energía es $2l+1$ degenerada



Dado l , m toma los valores

$$m = -l, -l+1, \dots, l-1, l$$